

## CLAIMS

What is claimed is:

1           1. A device for simulating slip of a wheel on a vehicle test bench according to the  
2 equation  $F_R = F_A \times C$ , wherein  $F_R$  is a frictional force,  $F_A$  is a contact force of the wheel,  
3 and  $C$  is a coefficient of friction, the device comprising:

4           a movable test surface to simulate rolling conditions of a wheel which contacts  
5 said test surface with a contact force  $F_A$ ; and

6           means for changing the contact force  $F_A$  in a predetermined manner.

1           2. The device for simulating slip of claim 1, wherein the means for altering the  
2 contact force  $F_A$  comprises a lifting/lowering device.

1           3. The device for simulating slippage of a wheel in a vehicle test bench of claim  
2 2, wherein the lifting/lowering device can vertically adjust a hub of the wheel while the  
3 wheel is rotating.

1           4. The device for simulating slip of claim 2, wherein the lifting/lowering device  
2 holds the wheel with a holding force and is controllable by one of hydraulic pressure,  
3 electrical signals, and linear motors, the device for simulating slip further comprising  
4 means for measuring the holding force, whereby the holding force can be used to  
5 determine the contact force.

1           5. The device for simulating slip of claim 2, wherein the lifting/lowering device  
2 can follow a tracking/steering angle and a kingpin angle of the wheel, whereby the

3 lifting/lowering device can secure the wheel in a direction transverse to the direction of  
4 travel.

1 6. The device for simulating slip of claim 2 further comprising:

2 a wheel adapter for coupling the wheel to the lifting/lowering device,

3 a bearing unit rotatable about a pivot axis so as to change the track of the

4 wheel, the wheel adapter being rotatably arranged in the bearing unit;

5 a mount pivotably mounted to joint blocks;

6 a plurality of connecting arms connecting the bearing unit to the mount;

7 linear drives for lifting and lowering in the joint blocks in linear guides in a  
8 predetermined way;

9 a supporting block on which the linear guides and the linear drives are

10 arranged; and

11 a base plate for attaching the supporting block to an underlying surface.

1 7. The device for simulating slip of claim 1 further comprising means for

2 changing the coefficient of friction.

1 8. The device for simulating slip of claim 7, wherein the means for changing the

2 coefficient of friction comprise a nozzle for introducing water between the wheel and the

3 surface of the test device.

1           9. The device for simulating slip of claim 2, further comprising a controller for  
2     controlling the lifting/lowering device, the controller being integrated into a controller of  
3     the vehicle test bench.

1           10. The device for simulating slip of claim 2 further comprising a plurality of  
2     lifting/lowering devices for respective wheels, and a controller for connecting the  
3     lifting/lowering devices.

1           11. A method of simulating slip of a wheel on a vehicle test bench comprising a  
2     movable test surface for simulating rolling conditions of a wheel which contacts said  
3     surface with a contact force  $F_A$ , said method comprising displacing the contact force  $F_A$   
4     from the wheel to a lifting device in a predetermined way by lifting the wheel off the  
5     surface as the wheel rotates.

1           12. The method of simulating slip of claim 11 comprising:  
2             completely displacing the contact force  $F_A$  from the surface to said lifting device  
3     by lifting the wheel completely off the surface;  
4             determining the absolute value of the contact force  $F_A$  by means of a measuring  
5     device while said wheel is completely off said surface;  
6             determining a maximum traction force  $F_Z$  which can be transmitted to the surface  
7     based on said absolute value;  
8             calculating a coefficient of friction  $C$  with the equation  $F_Z = F_A \times C$ , where  $F_A$  is  
9     the absolute value; and

10            setting the friction force  $F_R$  according to the equation  $F_R = F_A \times C$  by controlling  
11   the contact force  $F_A$ .

1            13. The method of simulating slip of claim 12 wherein said maximum tractive  
2   force  $F_z$  is changed in accordance with a predefined test program.

1            14. The method of simulating slip of claim 12 wherein said coefficient of friction  
2   is changed in accordance with a predefined test program.